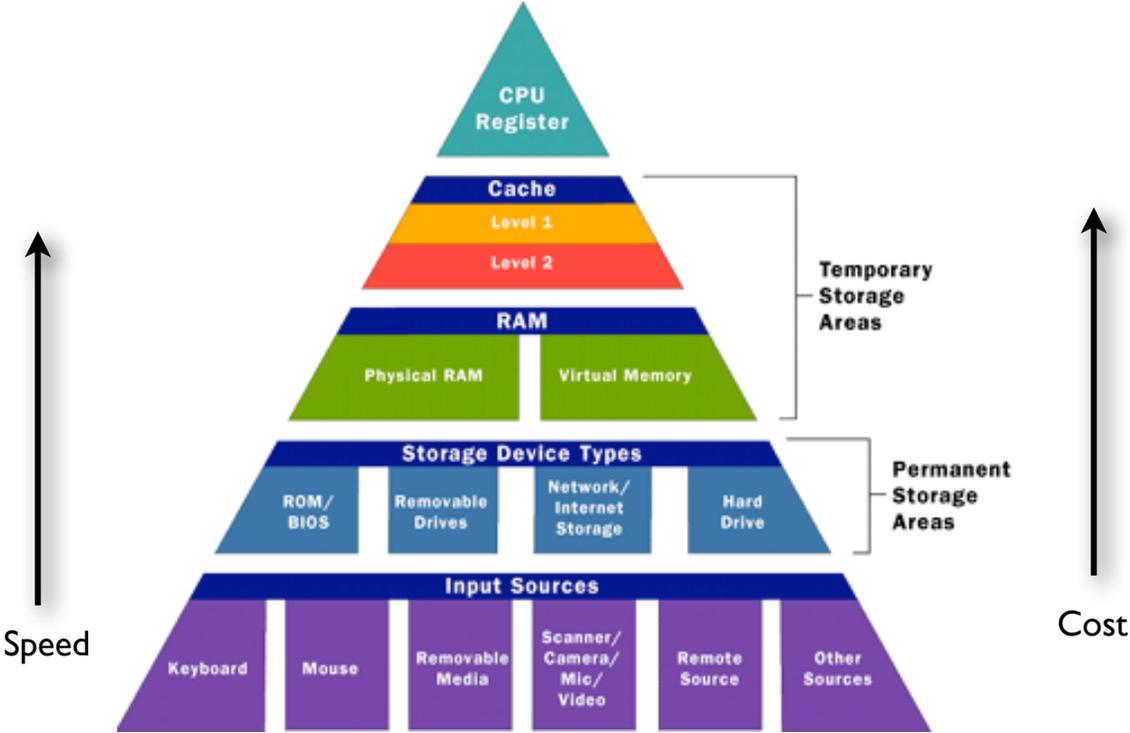


The Storage Hierarchy



Random Access Memory - RAM (Main memory)



RAM

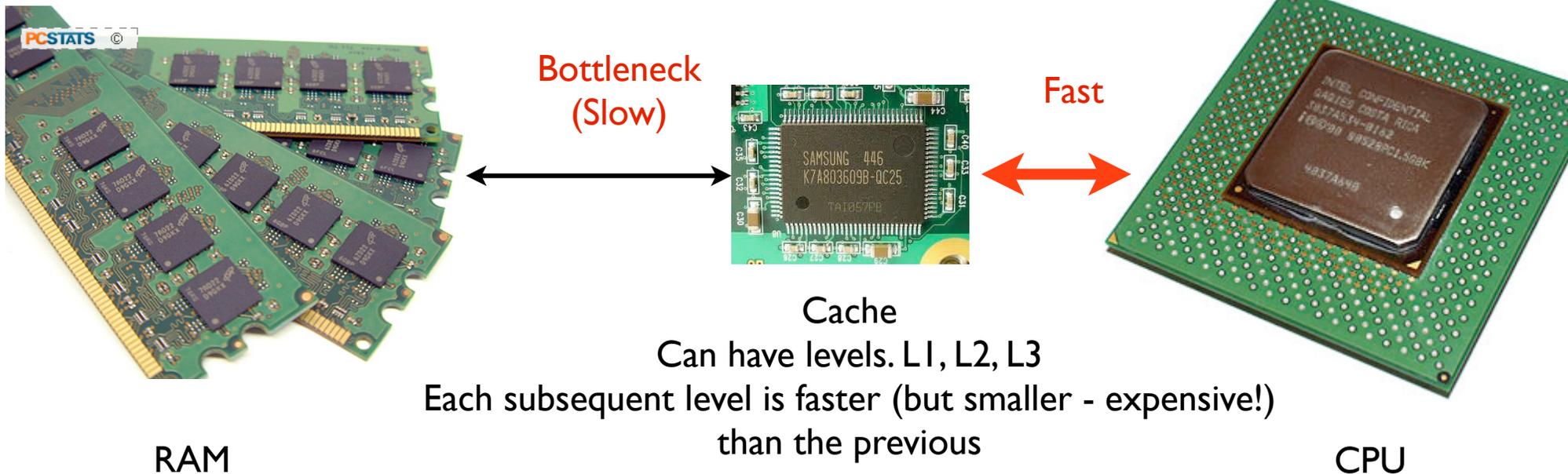
Bottleneck
(Slow)



CPU

CPU speed is much faster than the transfer speed between RAM and CPU; hence, if all data were only in RAM, the CPU would be idle most of the time

Cache



Cache/CPU speed is nearly the same as CPU speed;
Data should be continuously prefetched/pipelined to cache which then supplies CPU as needed.
Hence, the data flow between RAM/Cache/CPU should be predicted.
The instructions for the data flow are usually supplied by a compiler.
But you need to help it too!

Strategies for efficiency

- Registers: do maximum work at data already at registers before requesting new data
- Cache: maximum use of data already in cache; understand how data are stored in cache
- Data locality: priority access the data bits that already close to each other in memory before the bits that are far
- Input/Output: generally avoid at all costs; if must, do as much as possible at once rather than little bit at a time

Avoid Data Dependency

$$x = y + b$$

$$z = x + c$$

z depends on x



$$x = y + b$$

$$z = y + b + c$$

no dependency

Usually automatically done by a compiler when optimization is on

Avoid explicit integer power

$x = y^{**}3.0$ expensive power-function may be called



$x = y*y*y$

Can be automatically done by a 'smart' compiler

Avoid divisions

$$x = y / 2.$$

division can be much more expensive
than multiplication



$$x = 0.5 * y$$

Can be automatically done by a 'smart' compiler

Reduce computation of common subexpressions

$$x = y * (b / c)$$
$$z = f * (b / c)**2.5$$



$$t = b / c$$
$$x = y * t$$
$$z = f * t**2.5$$

Can be automatically done by a 'smart' compiler

Watch out for Loop Invariants

```
do i=l,n
```

```
  x(i) = y(i) + z(i)*a/c(i)/b
```

```
  h(n) = f *a
```

```
end do
```



```
tmp = a/b
```

```
do i=l,n
```

```
  x(i) = y(i) + z(i)*tmp/c(i)
```

```
end do
```

```
h(n) = f *a
```

a/b does not depend on i

h(n) does not depend on i

Look for conditions that dependent on loop index

```
do i=1,nx
  do j=1,ny
    if(x(j).gt.0) then
      y(i,j) = x(i) + z(i,j)*c(i)
    else
      y(i,j) = z(i,j)*b(i)
    end if
  end do
end do
```

Before

```
do j=1,ny
  if(x(j).gt.0) then
    do i=1,nx
      y(i,j) = x(i) + z(i,j)*c(i)
    end do
  else
    do i=1,nx
      y(i,j) = z(i,j)*b(i)
    end do
  end if
end do
```

After

Get boundary conditions outside the loop

```
do i=1,n
  if (i==1 .or. i==n) then
    x(i) = y(i)
  else
    x(i) = y(i)*d(i)
  end if
end do
```

Before

```
x(1) = y(1)
do i=1,nx
  x(i) = y(i)*d(i)
end do
x(n) = y(n)
```

After

Index Splitting

```
do i=1,n
  if (i<m) then
    x(i) = y(i)*c(i)
  else
    x(i) = y(i)*d(i)
  end if
end do
```

Before

```
do i=1,m-1
  x(i) = y(i)*c(i)
end do
do i=m,n
  x(i) = y(i)*d(i)
end do
```

After

Loop order exchange

Make 'slower' changing loop-index to be in outer loop,
fast index - inner loop

```
do i=1,nx
  do j =1,ny
    x(i,j) = y(i,j)+1
  end do
end do
```

Before

```
do j=1,ny
  do i =1,nx
    x(i,j) = y(i,j)+1
  end do
end do
```

After

In Fortran, array a(3,3) is stored as: a(1,1) a(2,1) a(3,1) a(1,2) a(2,2) a(3,2) a(1,3) a(2,3) a(3,3)

In C the order is reversed: a(1,1) a(1,2) a(1,3) a(2,1) a(2,2) a(2,3) a(3,1) a(3,2) a(3,3)

Loop fusion (register reuse)

Only if all arrays in the loop fit in cache (small)

```
do i=1,n
  x(i) = y(i)+1
end do
do i=1,n
  a(i) = x(i)+c
end do
do i=1,n
  d(i) = a(i)+y(i)
end do
```

Before

```
do i=1,n
  x(i) = y(i)+1
  a(i) = x(i)+c
  d(i) = a(i)+y(i)
end do
```

After

Loop fission (effective cache use)

Only if all arrays are large, so all don't fit in cache

```
do i=1,n
  x(i) = y(i)+1
  a(i) = x(i)+c
  d(i) = a(i)+y(i)
end do
```

Before

```
do i=1,n
  x(i) = y(i)+1
end do
do i=1,n
  a(i) = x(i)+c
end do
do i=1,n
  d(i) = a(i)+y(i)
end do
```

After

Avoid loop index dependencies

```
do i=1,n
  x(i) = x(i-1)*a(i)
  b(i) = x(i)*c(i)
end do
```

Before

```
do i=0,n-1
  y(i) = x(i)*a(i+1)
end do
do i=1,n
  x(i) = y(i)*c(i)
end do
```

After

avoid if's when can

```
if (x >= 1.) then  
    x = 1.  
elseif (x <= 0.) then  
    x = 0.  
end if
```

```
x=min(1.,max(0.,x))
```

Before

After

avoid if's when can

if (u(i) >= 0.) then

$$x(i) = u(i) * (x(i) - x(i-1))$$

else

$$x(i) = u(i) * (x(i+1) - x(i))$$

end if

$$v = \max(0., u(i)) * (x(i) - x(i-1)) + \& \\ \min(0., u(i)) * (x(i+1) - x(i))$$

Before

After

Never call a subroutine/function within large loop

```
do j=1,ny
  do i=1,nx
    ...
    y= fun(x(i,j))
  end do
end do
```

```
real function fun (x)
  x = x*cos(x)
end function fun
```

Before

Inlining

```
do j=1,ny
  do i=1,nx
    ...
    y= x(i,j)*cos(x(i,j))
  end do
end do
```

After

Steps in code development:

Never call a subroutine/function within large loop

```
do j=1,ny
  do i=1,nx
    ...
    call micro()
    ...
  end do
end do
```

Before

```
subroutine micro()
...
do j=1,ny
  do i=1,nx
    ...
  end do
end do
...
end subroutine micro
```

After

Some advise

- new code should go through initial test compiling with optimization off, uninitialized memory and array bound checks on;
- If the program fails after ported to another system or after not using the code for awhile, try running first with optimization off;
- Always try to use maximum compiler optimization; but make sure the results are similar (not the same) with lower optimization
- Use comments, sensible names for variables, indenting;
- One file per subroutine/module;
- Never use 'magic numbers'.